

Virtual Ring Routing

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- 8 Limitations and Future Directions

The Set-Up

Multi-hop routing algorithms describes a scheme for communication between devices.

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Main Concerns When Routing:

- Memory capacity constraints
- Over-reliance on specific nodes in the network
- Scalability
- Length of routing path

The Premise of VRR

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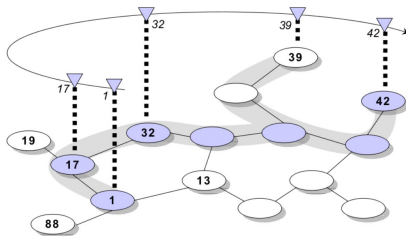


Figure: The underlying physical network and the virtual overlay (image from Wikipedia)

The Physical Network

An undirected graph $G = (V; E)$

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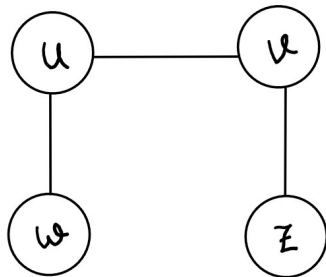
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$(u; v) \in E$ is a physical link

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Given a physical network $G = (V; E)$, we can construct a **virtual network** $G_V = (V; E_V)$, where E_V denotes **virtual links**.

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If $hu; vi \in E_V$, then $hv; ui \in E_V$.

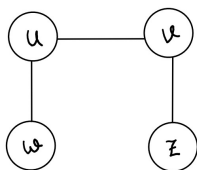
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If $hu;vi \in E_V$, then $hv;ui \in E_V$.



$hu;zi \in E_V$ is a virtual link, where $hu;zi = vl((u;v);(v;z))$

Identifier Space

To set up routing, we need an identifier space Ω :

- well-ordered set
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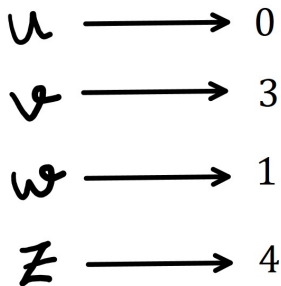
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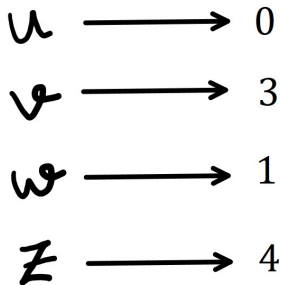
In VRR, we always take $\Omega = \mathbb{N}$ and assume the function assigns id randomly

Node to Id Mapping

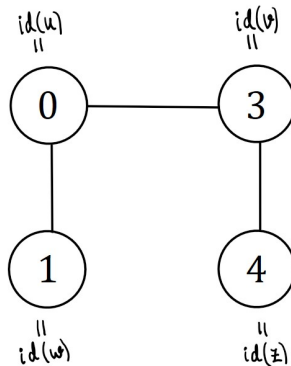


Node to Id Mapping

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Node to Id Mapping



We often use v or $id(v)$ to refer to the same node

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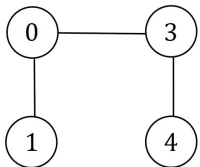
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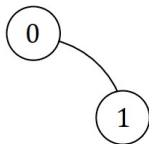
If $id(v)$ is the largest, then v_+ is the node in V with the smallest id

Note: It is always possible to create a virtual link between any two nodes in V since we require G to be connected

For Example...

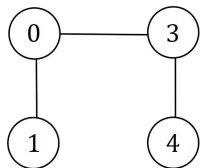


Physical Network

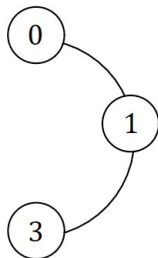


$$h_{0;1} = vl(0;1)$$

For Example...



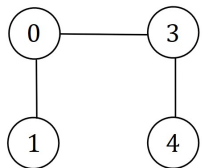
Physical Network



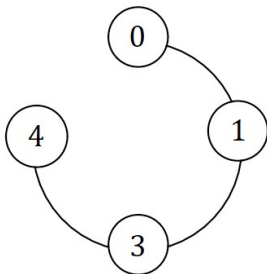
$$h_{0;1i} = vl(0;1)$$

$$h_{1;3i} = vl((1;0);(0;3))$$

For Example...



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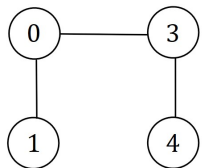


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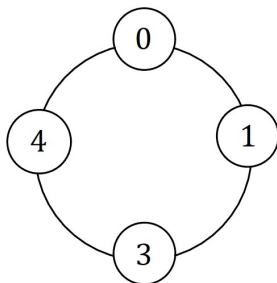
$$h_{1;3i} = vl((1;0);(0;3))$$

$$h_{3;4i} = vl(3;4)$$

For Example...



Physical Network



Virtual Network

$$h_{0;1i} = vl(0;1)$$

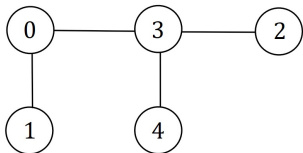
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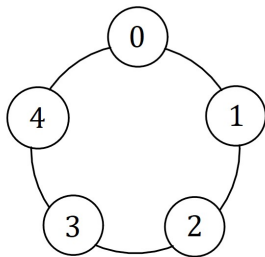
$$h_{4;0i} = vl((4;3);(3;0))$$

Another Node?

If we add another node then



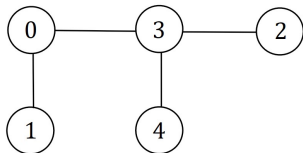
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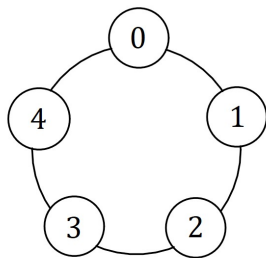
Virtual Network

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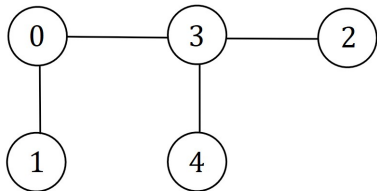


Virtual Network

$$h_{1;2i} = vl(h_{1;3i};(3;2))$$

$$h_{2;3i} = vl(2;3)$$

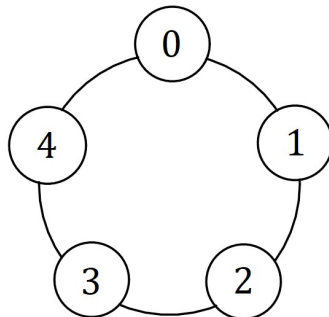
Physical and Virtual Neighbours



Physical Network

$$P_3 = f0;4;2g$$

$$V_3 = f4;2g$$



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Routing Table

Definition 2

The **routing table** at node $u \in V$ is a collection of 4-tuples (from, to, next hop, prev. hop) from $V \times V \times V \times V$ of routing paths that go through node u .

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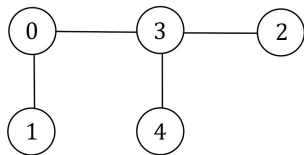
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- The prev. hop and next hop nodes must be physical neighbours of u
- There is one (and ONLY one) entry in the routing table of u for any path that starts, ends, or passes through u
- End_u denotes the set of all nodes in the "to" or "from" coordinate in an entry on the routing table of u other than u itself
i.e. all the nodes we know how to travel to from u

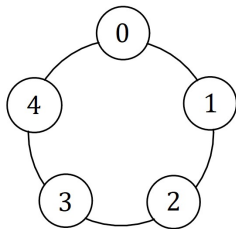
For Example...



Physical Network

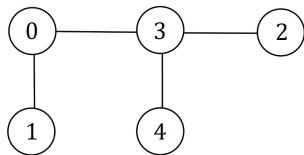
Routing Table at 3

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 2 | 3 | - | 2 |
| 4 | 3 | - | 4 |
| 0 | 3 | - | 0 |
| 4 | 0 | 0 | 4 |
| 1 | 2 | 2 | 0 |

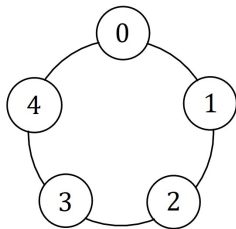


Virtual Network

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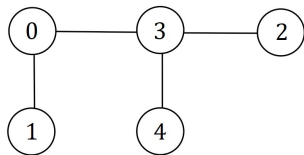
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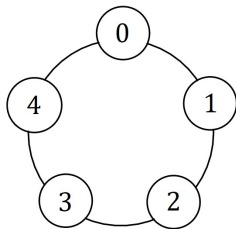
Routing Table at 2

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 2 | 3 | 3 | - |
| 2 | 1 | 3 | - |

For Example...



Physical Network



Virtual Network

Routing Table at 3

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 2 | 3 | - | 2 |
| 4 | 3 | - | 4 |
| 0 | 3 | - | 0 |
| 4 | 0 | 0 | 4 |
| 1 | 2 | 2 | 0 |

Routing Table at 2

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 2 | 3 | 3 | - |
| 2 | 1 | 3 | - |

Once the physical network is fixed, the routing table is fixed

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What should $h_2;0_i$ be?

The Routing Algorithm

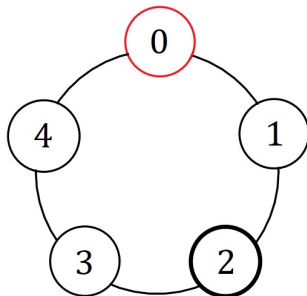
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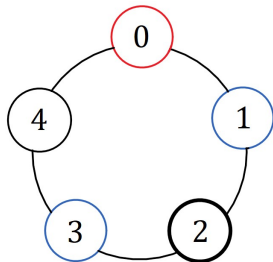
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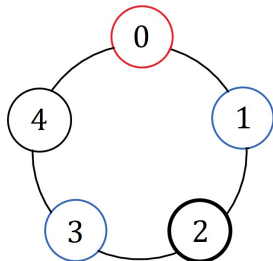
First Attempt

$$V_2 = f3;1g$$



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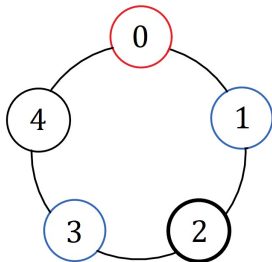
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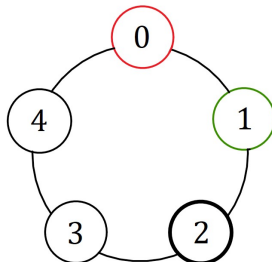
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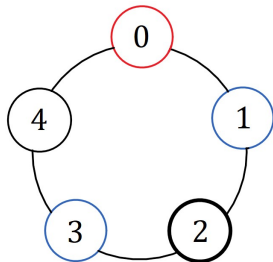


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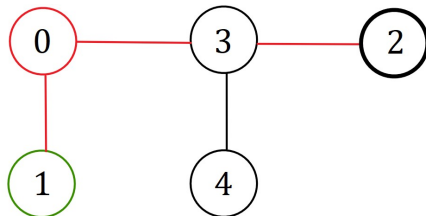
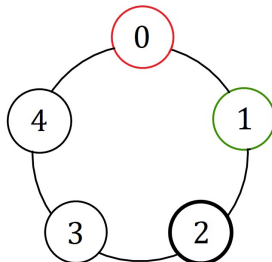


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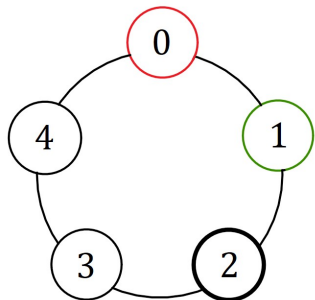
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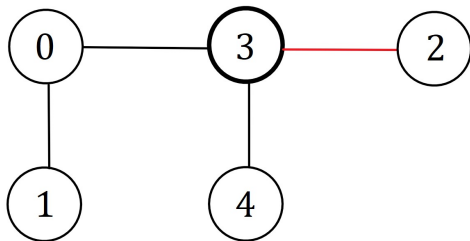
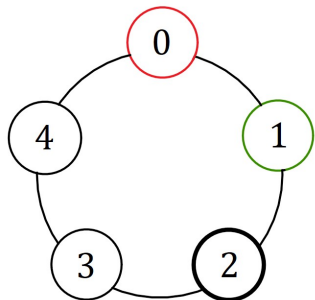
$$d(1;0) < d(3;0) \Rightarrow T^0 = 1$$



Second Attempt?

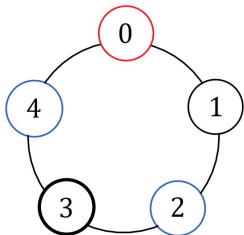


Second Attempt?



Comparing at Each Node

$$V_3 = f4;1g$$



Comparing at Each Node

$$V_3 = f(4; 1)g$$

$$d(4; 0) < d(2; 0) \Rightarrow T^0 = 4$$

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Third (And Hopefully Last) Attempt

Using the Routing Table

Routing Table at 3

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 2 | 3 | - | 2 |
| 4 | 3 | - | 4 |
| 0 | 3 | - | 0 |
| 4 | 0 | 0 | 4 |
| 1 | 2 | 2 | 0 |

Using the Routing Table

$\text{End}_3 = f 0; 1; 2; 4g$

Routing Table at 3

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 2 | 3 | - | 2 |
| 4 | 3 | - | 4 |
| 0 | 3 | - | 0 |
| 4 | 0 | 0 | 4 |
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The Actual Routing Path

Routing Table Entry for 0

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 4 | 0 | 0 | 4 |

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| from | to | next hop | prev. hop |
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Greedy Transition Vs. Non-Greedy Transition

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| from | to | next hop | prev. hop |
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| 2 | 3 | - | 2 |
| 4 | 3 | - | 4 |
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| 1 | 2 | 2 | 0 |

$$V_3 = f(4; 2g), T^0 = 0$$

Greedy Transition Vs. Non-Greedy Transition

Routing Table at 3

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 2 | 3 | - | 2 |
| 4 | 3 | - | 4 |
| 0 | 3 | - | 0 |
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| 1 | 2 | 2 | 0 |

$$V_3 = f 4; 2g, T^0 = 0$$

Routing Table at 2

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 2 | 3 | 3 | - |
| 2 | 1 | 3 | - |

$$V_2 = f 1; 3g, T^0 = 1$$

Greedy Transition Vs. Non-Greedy Transition

Routing Table at 3

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 2 | 3 | - | 2 |
| 4 | 3 | - | 4 |
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| 4 | 0 | 0 | 4 |
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$$V_3 = f 4; 2g, T^0 = 0$$

$T^0 \not\subseteq V_3$
Greedy Transition

Routing Table at 2

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 2 | 3 | 3 | - |
| 2 | 1 | 3 | - |

$$V_2 = f 1; 3g, T^0 = 1$$

$T^0 \subseteq V_2$
Non-Greedy Transition

Summarizing The Routing Algorithm

Given a source-target pair s and t , we can summarize the routing algorithm as follows:

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Once we reach an intermediate target x_i , we set the intermediate target from End_{x_i}

What exactly is a better node?

x is a better node if $d(x; T) < d(T^0; T)$, where T is the target, T^0 is the intermediate target

Note: We want to choose the "best" possible,
i.e. the one that gets us closest to the target

Some Edge Cases

Some Edge Cases

Remarks About the Intermediate Target(s)

Each new intermediate target $\bar{\Gamma}^0$ is always closer to the target T than the previous one.

At any node u , the current intermediate target is closer to the target than u or equidistant

Once we set $\bar{\Gamma}^0 = T$, there are no more new intermediate targets

Properties of This Routing Algorithm

Proposition 1

VRR schemes using greedy routing exhibit no loops

Proof: If we have a loop, we must visit the same node twice, say

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At time 2

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- 6 Current Research
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- 8 Limitations and Future Directions

Benefits of VRR

Each node only stores local info; less memory used relative to increase in size of physical network

Flexible since adding/ removing a node only affects nodes that had that node in their routing table

Limitations of VRR

Routing path may not be the shortest path

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Definition 3

We define stretch as the ratio between the actual routing path and the shortest possible path on the physical network

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Consider the following example

Stretch

Suppose again that we are routing $2; 0i$. Our ring:

The Actual Routing Path

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 2 | 3 | 3 | - |
| 2 | 1 | 3 | - |

$$d(1;0) < d(3;0)$$
$$\Rightarrow T^0 = 1$$

The Actual Routing Path

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 3 | 5 | 5 | - |
| 3 | 4 | 4 | - |
| 3 | 2 | 2 | - |
| 2 | 1 | 4 | 2 |
| 4 | 5 | 5 | 4 |

$$\begin{aligned} & d(5;0) \quad d(1;0) \\ \Rightarrow & T^0 = 1 \end{aligned}$$

The Actual Routing Path

| from | to | next hop | prev. hop |
|------|----|----------|-----------|
| 4 | 3 | 3 | - |
| 4 | 1 | 2 | - |
| 4 | 5 | 3 | - |

$$\begin{aligned} & d(5;0) \quad d(1;0) \\ \Rightarrow & T^0 = 1 \end{aligned}$$

Stretch

$$L_A = 5$$

Stretch

$$L_A = 5$$

$$L_S = 3$$

Stretch

$$L_A = 5$$

$$L_S = 3$$

Stretch is 5:3

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Current Research: Careful Study of Stretch

The questions:

How can we study stretch?

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How does stretch change α ! 1

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What other factors might affect stretch?

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How can we study stretch?

How does stretch change as λ ! 1

What other factors might affect stretch?

The issues:

Setting up a good model for the physical network

Current Research: Careful Study of Stretch

The questions:

How can we study stretch?

How does stretch change as $n \rightarrow 1$?

What other factors might affect stretch?

The issues:

Setting up a good model for the physical network

Computing the expected path length

The virtual network for large N

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Physical Network as a Ring

When the physical network is also a ring, we call it a physical ring.

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There are only two physical neighbours

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There are only two physical neighbours

We can consider the physical ring a permutation of the virtual ring

Stretch on a Ring

Proposition 2

If the physical network is a ring with $N > 3$ nodes, then the maximum stretch for any routing path is $\frac{N-2}{2}$

Proof of Prop'n 2

Proof: Consider source-target pair S and T . Suppose that, on the physical ring, $d(S; T) = k$ 2

Figure: The Physical Ring

Proof of Prop'n 2

Proof: Consider source-target pair s and T . Suppose that, on the physical ring, $d(S; T) = k \cdot 2$

Figure: The Physical Ring

By prop'n 1, the actual routing path either travels the minor arc or the major arc.

If we travel the minor arc then

$$\frac{L_A}{L_S} = \frac{k}{k} = 1$$

Figure: The Physical Ring

If we travel the minor arc then

$$\frac{L_A}{L_S} = \frac{k}{k} = 1$$

If we travel the major arc then

$$\frac{L_A}{L_S} = \frac{N}{k} \frac{k}{k}$$

Figure: The Physical Ring

If we travel the minor arc then

$$\frac{L_A}{L_S} = \frac{k}{k} = 1$$

If we travel the major arc then

$$\frac{L_A}{L_S} = \frac{N - k}{k}$$

Figure: The Physical Ring

This ratio is maximized when
 $k = 2$

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Limitations of the Physical Ring

Not practical since relatively poor connectivity

Limitations of the Physical Ring

Not practical since relatively poor connectivity
Even the shortest paths are long

Explore other physical network models

- Explore other physical network models
- Trying to formulate routing algorithm into Markov Chain process or as (sub)martingales and apply related theorems

Thanks for listening!
Any questions?

To better understand the mechanics of VRR:

M. Caesar, M. Castro, E. B. Nightingale, G. O'Shea, and A. Rowstron. Virtual ring routing: Network routing inspired by DHTs. In *ACM annual conference of the Special Interest Group on Data Communication (SIGCOMM)*, pages 351–362, 2006.

To read about other proofs related to VRR:

Malkhi, D., Sen, S., Talwar, K., Werneck, R. F., and Wieder, U. (2009). Virtual ring routing trends. In *Proceedings of the 23rd international conference on distributed computing*, Berlin, Heidelberg.